

# MATCAS

a **MAT**lab tool using **C**oefficient **A**pproximation for the automatic solution of multichannel Schrödinger equations

*Copyright 2012 Veerle Ledoux  
Department of Applied Mathematics and Computer Science  
Ghent University*

## WHAT

A Matlab tool for the automatic computation of bound-state eigenvalues and wavefunctions of coupled-channel Schrödinger equations. The user may specify the required eigenvalue by its index.

Details on the numerical methods can be found in:

V. Ledoux, M. Van Daele, Automatic computation of quantum-mechanical bound states and wavefunctions (2012).

## PROGRAMMING LANGUAGE

Tested with Matlab(R) version newer than 6.5. However, in principle, any recent version of Matlab(R) should work.

## HOW TO START

Download the package from <http://www.nummath.ugent.be/SLsoftware>

To run MATCAS the source files must be integrated into the Matlab path. This can be achieved by using the `addpath` command of Matlab. Or change your current folder to the MATCAS folder. To run the example.m files, enter e.g. `example1` in the Matlab command window.

## STRUCTURE AND USAGE

The package consists of several .m files: some example driver scripts and two files containing the Matlab functions `computeEigenvalues` and `computeEigenfunction`. Some additional auxiliary functions are collected in the folder called `source`. A user of the package will, however, not call a function from the source folder directly.

- `example1.m` / `example11.m`

example driver scripts

Each `example.m` file computes the eigenvalues and eigenfunctions of a specific Schrodinger problem. The `example.m` files illustrate how to specify the problem and how to call the functions `computeEigenvalues` and `computeEigenfunction`.

As an example we consider the problem from [L.Gr. Ixaru, Phys. Rev. A 77 (2008) 064102] which has known eigenvalues and solutions. The  $2 \times 2$  matrix potential for  $x \geq 0$ , is given by

$$V_{1,1}(x) = V_{2,2}(x) = V_{PT}(x; 45, 1) + V_{PT}(x; 39/2, 1/2) \quad (1)$$

$$V_{1,2}(x) = V_{2,1}(x) = V_{PT}(x; 45, 1) - V_{PT}(x; 39/2, 1/2) \quad (2)$$

where  $V_{PT}$  is the Pöschl-Teller potential

$$V_{PT}(x; \nu, \alpha) = -\nu / \cosh^2(\alpha x).$$

The wavefunction tends to zero when  $x \rightarrow +\infty$ . In our experiments the infinite integration interval  $x \geq 0$  has been cut at  $x = 30$ . The following code computes some eigenvalues and an eigenfunction of this problem.

```
% TEMPLATE

%Specify the endpoints of the integration interval:
system.a=0;
system.b=30;

%Specify the coefficient matrices of the boundary conditions:
system.A1=eye(2);
system.A2= zeros(2,2);
system.B1=eye(2);
system.B2= zeros(2,2);

%potential matrix function (function handle)
system.V=@potentialMatrix;

%Use the function computeEigenvalues to computes eigenvalues with specified index.
%Here indices 0 to 10, and input tolerance 1e-8
[EigvData,meshData]=computeEigenvalues(system,0,10,1e-8);

%The structure EigvData contains information on the computed eigenvalues:
disp(['Number of intervals in the mesh: ' num2str(length(meshData.h))]);
disp(sprintf('k \t E_k \t \t \t ErrEst \t status'))
for i=1:length(EigvData.eigenvalues)
    disp(sprintf('%-3.0f \t %-16.12f \t %-2.0e \t \t %d', EigvData.indices(i),...
        EigvData.eigenvalues(i), EigvData.errorEstimations(i),EigvData.status(i)));
end

%make plots of the eigenfunction corresponding to the first eigenvalue which
%has multiplicity 1
[x,Y,YP]=computeEigenfunction(system,meshData,EigvData.eigenvalues(1),1);
figure
plot(x,Y(1,:),1))
hold on
plot(x,Y(2,:),1),'r')
title('Eigenfunction')
legend('y_1(x)', 'y_2(x)')
hold off
figure
plot(x,YP(1,:),1))
hold on
plot(x,YP(2,:),1),'r')
hold off
xlabel('x')
title('First derivative of eigenfunction')
legend('y''_1(x)', 'y''_2(x)')

function r=potentialMatrix(x)
    %returns the potential matrix evaluated in x
```

```

%x may be a vector of values: make sure that the entries are vectorized, e.g.
% x.^2 instead of x^2.
r=zeros(2,2,length(x));
r(1,1,:)=-45./cosh(1*x).^2-(39/2)./cosh(1/2*x).^2;
r(2,2,:)=-45./cosh(1*x).^2-(39/2)./cosh(1/2*x).^2;
r(1,2,:)=-45./cosh(1*x).^2+(39/2)./cosh(1/2*x).^2;
r(2,1,:)=-45./cosh(1*x).^2+(39/2)./cosh(1/2*x).^2;
end

```

- `computeEigenvalues.m`.

This .m-file implements the `computeEigenvalues` function:

```

[EigvData,meshData]=computeEigenvalues(system,kmin,kmax,tol)
INPUT:
- system: a structure containing information on the Schrodinger problem
    system.a, system.b: endpoints of the integration interval
    system.A1,system.A2:
    system.B1,system.B2: parameters of the boundary conditions
    system.V: function handle to the potential matrix
        function
- kmin, kmax: lowest and highest index of the range of eigenvalues
    to be computed
- tol: user input tolerance (~ relative error in the eigenvalue
    approximations)
OUTPUT:
- eigvData: a Matlab structure
    eigvData.eigenvalues = vector containing the eigenvalue
        approximations
    eigvData.status = vector of same length as eigvData.eigenvalues
    eigvData.status(i)= 1 : no difficulties detected in the
        approximation of the i-th eigenvalue
    eigvData.status(i)= -1: the newton-raphson process didn't
        converge to an eigenvalue,
        try a lower input tolerance
    eigvData.status(i)= -2: too many iterations in the newton-
        raphson process. The requested accuracy
        may not have been reached.
    eigvData.indices = eigenvalue indices

- meshData: structure collecting all data associated to the mesh
    constructed
    meshData.tol : expected accuracy for the results
        computed over this mesh
    meshData.v0: vector of V_0 matrices, length of the vector
        equals the number of mesh intervals
    meshData.v1: vector of {\bar V}_1 matrices, length of the vector
        equals the number of mesh intervals
    meshData.v2: vector of {\bar V}_2 matrices, length of the vector
        equals the number of mesh intervals
    meshData.h: vector containing the length of the mesh intervals
    meshData.dimat: vector of D matrices (orthogonal matrix
        used by the diagonalization process), the length of
        the vector equals the number of mesh intervals
    meshData.cu,cup,cv,cvp: C-coefficients used by the
        sixth order CP algorithm

```

- `computeEigenfunction.m`

This .m-file implements the `computeEigenfunction` function:

```

function [x,YM,YPM]=computeEigenfunction(system,md,E,multiplicity)
%computes the eigenfunctions and their first order derivatives corresponding
% to the eigenvalue E in the meshpoints of the mesh given by the input argument md.
OUTPUT:  x : vector of x-values (=meshpoints) where the eigenfunctions were
          evaluated
          YM: 3-dim matrix (n times nsteps times multiplicity)
               contains information on the eigenfunctions
               YM(i,j,k) = i'th element (1<=i<=dimension n of the system) in
                           the k'th eigenfunction evaluated in the jth meshpoint .
               Each YM(:,k) with ( 1<= k <= multiplicity ) represents an
               eigenfunction.
          YPM: similar for the first order derivatives

```

NOTE: the eigenfunction and its derivative are only evaluated in the meshpoints (the values of these points are returned by the function `computeEigenfunction` in the vector `x`). This may not be sufficient to produce a nice smooth plot of a higher eigenfunction. The evaluation of the eigenfunctions in user specified points is future work.

- `source\computeVcoeffs.m`

The function `computeVcoeffs` returns the coefficient matrices  $\mathbf{V}_m$  in the polynomial approximation of degree 2 underlying the sixth order CP scheme:

$$\mathbf{V}(x_i + \delta) \approx \sum_{m=0}^2 \mathbf{V}_m h^m P_m^*(\delta/h_i)$$

with  $P_m^*(\delta/h_i)$  the shifted Legendre polynomials and the matrix weights  $\mathbf{V}_m$  given by the method of least squares:

$$\begin{aligned} \mathbf{V}_0 &= \frac{1}{h_i} \int_0^{h_i} \mathbf{V}(x_i + \delta) d\delta, \\ \mathbf{V}_m &= \frac{(2m+1)}{h_i^{m+1}} \int_0^{h_i} \mathbf{V}(x_i + \delta) P_m^*(\delta/h_i) d\delta, \quad m = 1, 2. \end{aligned}$$

These weights are computed by a Gauss-Legendre quadrature.

- `source\constructMesh.m`

This function implements the automatic stepsize selection algorithm.

- `source\getBracket.m`

This function generates a good initial guess for the Newton-Raphson procedure which is used in the eigenvalue shooting process. The Prüfer procedure is applied to generate reasonably tight upper and lower bounds for the eigenvalue  $E_k$  sought, i.e. a bracket  $[\hat{E}, \bar{E}]$  is determined such that  $\mathcal{I}(\hat{E}) = k$  and  $\mathcal{I}(\bar{E}) = k+1$  or  $\bar{E} - \hat{E} < tol$ .  $E = (\hat{E} + \bar{E})/2$  is then passed as the initial trial value for the eigenvalue  $E_k$ .

- `source\getIndex.m`

This function returns the value of the indexing function  $\mathcal{I}(E)$  and thus implements the numerical Prüfer procedure.

- `source\getTransferMatrices.m`

This function returns the entries  $\mathbf{U}, \mathbf{U}', \mathbf{W}, \mathbf{W}'$  of the propagation matrix for the sixth order CP scheme, which are given by:

$$\mathbf{U}^D(h_i) = \boldsymbol{\xi}(\mathbf{Z}) + \sum_{m=1}^2 \mathbf{C}_m^{(U)} \boldsymbol{\eta}_m(\mathbf{Z}), \quad (3)$$

$$h_i(\mathbf{U}^D)'(h_i) = \mathbf{Z} \boldsymbol{\eta}_0(\mathbf{Z}) + \sum_{m=0}^2 \mathbf{C}_m^{(U')} \boldsymbol{\eta}_m(\mathbf{Z}), \quad (4)$$

$$\mathbf{W}^D(h_i)/h_i = \boldsymbol{\eta}_0(\mathbf{Z}) + \mathbf{C}_2^{(W)} \boldsymbol{\eta}_2(\mathbf{Z}), \quad (5)$$

$$(\mathbf{W}^D)'(h_i) = \boldsymbol{\xi}(\mathbf{Z}) + \sum_{m=1}^2 \mathbf{C}_m^{(W')} \boldsymbol{\eta}_m(\mathbf{Z}) \quad (6)$$

with

$$\begin{aligned}
\mathbf{C}_1^{(U)} &= -\bar{\mathbf{V}}_1/2 + [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_0]/24 \\
\mathbf{C}_2^{(U)} &= -\bar{\mathbf{V}}_1^2/24 + [4\bar{\mathbf{V}}_1 - 3\bar{\mathbf{V}}_2, \bar{\mathbf{V}}_0]/24 \\
\mathbf{C}_0^{(U')} &= \bar{\mathbf{V}}_2/2 + [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_0]/24 - [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_2]/120 \\
\mathbf{C}_1^{(U')} &= -3\bar{\mathbf{V}}_2/2 - \bar{\mathbf{V}}_1^2/24 + [\bar{\mathbf{V}}_1 - \bar{\mathbf{V}}_2, \bar{\mathbf{V}}_0]/8 \\
\mathbf{C}_2^{(U')} &= -7\bar{\mathbf{V}}_1^2/24 + [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_2]/8 + [3\bar{\mathbf{V}}_2, \bar{\mathbf{V}}_0] \\
\mathbf{C}_2^{(W)} &= -\bar{\mathbf{V}}_2/2 + [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_0]/24 \\
\mathbf{C}_1^{(W')} &= \bar{\mathbf{V}}_1/2 + [\bar{\mathbf{V}}_1, \bar{\mathbf{V}}_0]/24 \\
\mathbf{C}_2^{(W')} &= -\bar{\mathbf{V}}_1^2/24 + [-2\bar{\mathbf{V}}_1 + 3\bar{\mathbf{V}}_2, \bar{\mathbf{V}}_0]/24
\end{aligned}$$

For notational brevity in the  $\mathbf{C}_m$  matrices, the upper label  $D$  has been suppressed and we introduced  $\bar{\mathbf{V}}_s = \mathbf{V}_s h_i^{s+2}$ ,  $s = 0, 1, 2$  and the matrix commutator notation  $[\mathbf{A}, \mathbf{B}] = \mathbf{AB} - \mathbf{BA}$ .

- `source\shootForEigenvalue.m`

This function implements the shooting algorithm

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**Algorithm 1** Shooting for the eigenvalue  $E_k$

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- 1: Input: a trial value  $E$ , a mesh  $a = x_0 < x_1 < \dots < x_N = b$ , with stepsizes  $h_i = x_{i+1} - x_i$ .
  - 2: Choose a meshpoint  $c = x_m$ ,  $0 \leq m \leq N$  as the matching point.
  - 3: Set up initial values for  $\Psi_L$  and  $\Psi_R$  satisfying the boundary conditions at  $a$  and  $b$  respectively.
  - 4: **repeat**
  - 5:   **for**  $i = 0$  to  $m - 1$  **do**
  - 6:     Compute  $\mathbf{U}(h_i), \mathbf{W}(h_i), \mathbf{U}'(h_i), \mathbf{W}'(h_i)$  by the 6th order CA method.
  - 7:     Propagate  $\Psi_L$  over the interval  $[x_i, x_{i+1}]$ :  
 $\Psi_L(x_{i+1}) = [\mathbf{W}(h_i) + \mathbf{U}(h_i)\Psi_L(x_i)][\mathbf{W}'(h_i) + \mathbf{U}'(h_i)\Psi_L(x_i)]^{-1}$
  - 8:   **end for**
  - 9:   **for**  $i = N$  down to  $m + 1$  **do**
  - 10:     Compute  $\mathbf{U}(h_i), \mathbf{W}(h_i), \mathbf{U}'(h_i), \mathbf{W}'(h_i)$  by the 6th order CA method.
  - 11:     Propagate  $\Psi_R$  over the interval  $[x_{i-1}, x_i]$ :  
 $\Psi_R(x_{i-1}) = [-\mathbf{W}(h_i) + \mathbf{W}'(h_i)\Psi_R(x_i)][\mathbf{U}(h_i) - \mathbf{U}'(h_i)\Psi_R(x_i)]^{-1}$
  - 12:   **end for**
  - 13:   Adjust  $E$  to solve the equation  $\det(\Psi_L(c) - \Psi_R(c)) = 0$ .
  - 14: **until**  $E$  sufficiently accurate (e.g. until the difference between two subsequent  $E$  values is smaller than some user input tolerance)
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